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Steganalysis using Partially Ordered Markov Models

Dr. Jennifer Davidson^a Jaikishan Jalan^b

^a Dept. of Mathematics, Dept. of Electrical & Computer Engineering ^b Former student, Dept. of Computer Science

Iowa State University, Ames, IA



Overview of Talk

- Use of stochastic models for features in steganalysis
 - Feature selection in steganalysis: informal approach
 - Motivation to use stochastic models for steganalysis
- Define *partially ordered Markov models* and give a general problem solution for creating features for steganalysis using POMMs
- Experiments
 - Five JPEG embedding algorithms
 - Three additional steganalyzers
- Results
- Future research

Statistical steganalysis feature development

- The image A is modeled as a collection of random variables (r.v.s) with a probability distribution P(A)
- A vector F(A) = (f₁(A), K, f_n(A)) of *feature values* is calculated from the image pixels, where n << the number of pixels in the image
- The functions $\{f_i(A)\}_{i=1}^n$ are chosen by the steganalyst using domain knowledge
- Features are selected to exploit known differences between stego and cover characteristics and used in targeted or blind pattern recognition systems

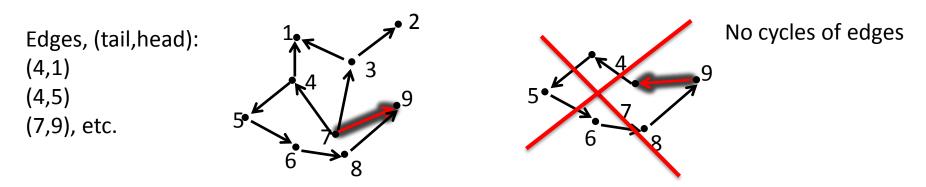
Statistical steganalysis feature development

- Previously used probability distributions for features in steganalysis
 - Generalized Gaussian distribution for modeling mode histograms of DCT coefficients
 - Markov chains for pixels adjacent in the DCT domain and in the spatial domain (Shi et al. 2007, Pevný 2009)
 - We were motivated to investigate other stochastic models that could provide theoretical foundation for modeling steganographic changes to image



Acyclic directed graphs and partially ordered sets

• **Definition**. Let (*V*,*E*) be a finite acyclic directed graph:



• **Definition**. Let (V, \leq) be a *partially ordered set (poset)* where \leq is a binary operation on V:

1. $w \le w$ for all $w \in V$ (reflexivity)

2. $w \le x, x \le y \Longrightarrow w \le y$ (transitivity)

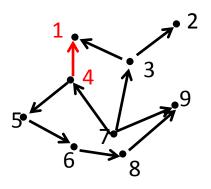
3. If $w \le x$ and $x \le w$ then w = x (anti - symmetry)

• Example: V =all subsets of a set, $\leq = \subseteq$ (set inclusion)



Acyclic directed graphs and partially ordered sets

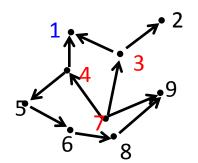
- **Def.** For V_i , $V_j \in (V, \le)$, V_i is covered by V_j if $V_i < V_j$ and $V_i < V_k < V_j$ for no k.
- Given graph (V, E), construct poset (V, \leq) by
 - (*i*,*j*) ε *E* implies V_i is covered by V_j in (*V*,≤).
 - This defines a partial order on V
 - In this case we write $V_i < V_j$
- Edge (4,1) defines the relation between
 V₄ and V₁, so V₄ is covered by V₁
 and V₄ < V₁



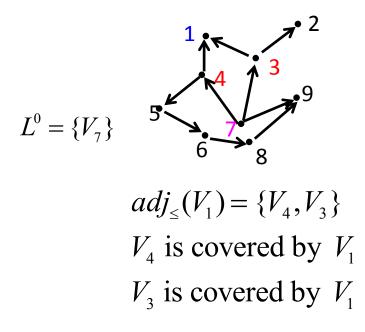


Definitions

 $cone(B) = \{C \in V : C \le B, C \ne B\}$ $adj_{\le}(B) = \{C : (C,B) \in E\} = all elements covered by B$ $L^0 = set of minimal elements in V (no edges incoming to vertices)$



 $cone(V_1) = \{V_4, V_7, V_3\}$ $V_4 \text{ is covered by } V_1$ $V_7 \text{ is covered by } V_4$ $V_3 \text{ is covered by } V_1$



Definition of partially ordered Markov model

 Def. Let V be a set of random variables and B ε V, where V is a finite acyclic digraph (V,E) with poset (V,≤). Let

 $Y_{B} = \{C : B \text{ and } C \text{ are not related under } \leq \}$

Then (V, \leq) is called a *partially ordered Markov model* (POMM) if for any $B \in V \setminus L^0$ and any subset $U_B \subseteq Y_B$ we have

$$P(B \mid cone(B, U_B) = P(B \mid adj_{\leq}(B))$$

• The lower adjacent neighbors describe the "Markovian" property of the model

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Our interest

- $A = \{A_{ij} : 1 \le i \le N, 1 \le j \le M\}$: set of r.v.s on array
- S = {S₁,..., S_t} is a collection of subsets of r.v.s in A where each S_k is an ordered set
- Example: S^h , $S_1^h = \{A_{11}, A_{12}\}, S_2^h = \{A_{12}, A_{13}\}$, etc.
- Introduce a function f: S → R the set of real numbers that gives quantifying information about the subsets
- Example: $f(w_1, w_2) = w_1 w_2$ $f(S_i^h) = f(A_{j,k}, A_{j,k+1}) = A_{j,k} - A_{j,k+1}$

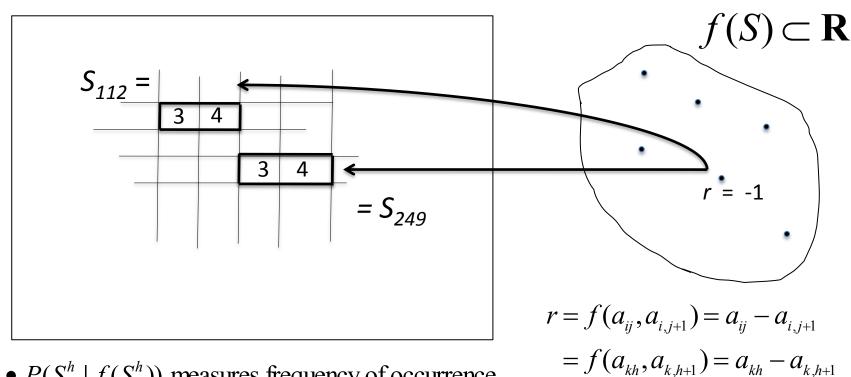
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Our interest

- Create an acyclic digraph: $V = S \cup f(S)$, $E = \{E_i\}$ where $E_i = (f(S_i), S_i)$ and has tail on $f(S_i)$ and head on S_i
- We call this the *function-subset acyclic digraph*, or *f-S*
- We use this acyclic digraph to construct a sequence of POMMs whose conditional probabilities are used as features
- If f is a useful function for the steganalyst, then the quantity $P(S_k|f(S_k))$, which is a measure of the frequency of occurrence of the pre-image of $f(S_k)$, can be used to distinguish between cover and stego images
- This is the motivation for using the *f*-*S* partial order/acyclic digraph as defined earlier



Diagram of *f*-*S* acyclic digraph



- $P(S_k^h | f(S_k^h))$ measures frequency of occurrence of 3 4 given the difference value of -1
- P(*|*) defines the POMM associated with thi horizontal f S model



Features

- Collect information in four directions: **S**^h, **S**^v, **S**^d, **S**^m
- Create a POMM for each of the four directions P^h, P^v, P^d, P^m
- Calculate conditional probabilities P^{*}(S^{*}_k|f(S^{*}_k)), * ε {h,v,d,m} using the quantized DCT array of values thresholded by value T
- Each direction gives a (2T + 1) x (2T + 1) feature matrix F^{*}(w,z) = P^{*}(w,z|f(w,z)
- Average over four directions to get (2T + 1)² intrablock feature values:

$$F^{\text{intra}}(w,z) = \frac{1}{4} \sum_{* \in \{h,v,d,m\}} P^*(w,z \mid w-z)$$



Features

- Also construct POMMs using interblock values from quantized DCT array in a similar manner
- There are 8*8 = 64 mode arrays
- Average over the 64 feature matrices to get another (2T + 1)² feature values

$$F^{\text{inter}}(w,z) = \frac{1}{64} \sum_{* \in \{h,v,d,m\}} P^{*}(w,z \mid w-z)$$

Total number of features = 2*(2T + 1)² and it depends on the value T



Experiments

- Used four databases: BOWS2 (10,000 images), a camera database (3164), Corel (8185), NRCS (2375)
- Created training and testing data from these DB
- Used three additional state of the art steganalyzers:
 - Shi's Markov model using intrablock values (Shi et al, 2007); "Markov324" (324 features)
 - Shi's Markov model using both intra and interblock values (Shi et al, 2008); "Markov486"
 - Pevný merged model with extended DCT features plus calibrated Markov values from Markov324 (Pevný et al., 2007) "Merged"



- Classifier: soft margin support vector machine with Gaussian kernel and grid-search method to determine training parameters (LIBSVM)
- Five embedding algorithms at four embedding rates each: Jsteg, OutGuess, F5, StegHide, and JPHide; bpnz = 0.05, 0.1, 0.2, 0.4 (except last one was omitted for OutGuess)
- Calculated detection accuracy using binary classifiers



Method

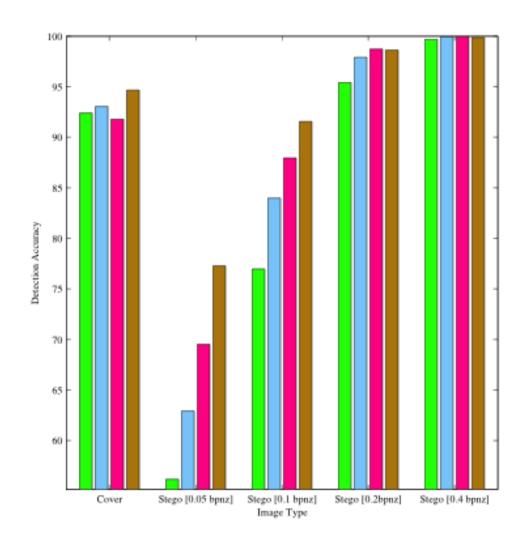
- Tried five values for *T*: *T* = 1, 2, 3, 4, 5
- Overall best detection accuracy was achieved for T = 3; this gives a total of 98 features
- Developed binary classifiers for each case, total of 24 binary classifiers
- Half of data was used for training, other half for testing
- Tested each database separately



Results and discussion

StegHide using BOWS2 database



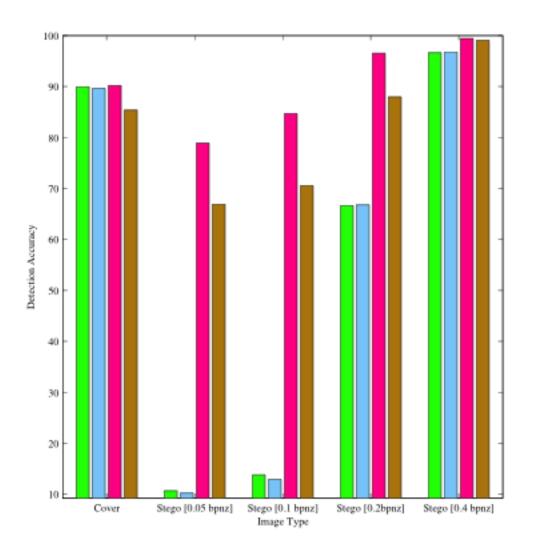




Results and discussion

JPHide using Camera database







Discussion

- POMMs perform better almost without exception than either Markov model particularly at the lower embedding rates
- POMM performed better than Merged for Outguess and StegHide across all databases and all embedding levels
- Merged performed better than POMMs at lower embedding rates for F5 and JPHide across all databases
- At highest levels of embedding all algorithms performed similarly well



Discussion

- Another way to measure performance
- Criterion: Performed >greater than 1% better than any detector, or within 1% of top detector, on cover, 0.05 and 0.1 embedding rates (most difficult to detect)
- POMM: 17% of the time
- Merged: 18% of the time
- Other two steganalyzers were far beneath that



Conclusion

- Introduction of new modeling tool to measure embedding changes
- Allow steganalyst to create functions to detect changes
- Can use other measures of the probability distribution for features such as moments mean, variance, etc.
- Possibility of using joint pdf in detection (MLE), as joint pdf is computationally efficient
- 98 features give equivalent detection to Merged steganalyzer
- Current and future research: double compression detector for use in police forensic GUI software
- Use of POMMs for spatial embedding detection
- Use of other functions *f* and subsets *S*