### Detection of Copy–Rotate–Move Forgery Using Zernike Moments

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# Introduction (1/2)

### Improvement of image processing softwares

- > People can easily alter digital images
- > Important to verify the authenticity of digital images

### Copy-Move forgery

- > Copies a part of the image
- > Pastes it into another part of the image
- Example of Copy-move forgery





## Introduction (2/2)

### Copy-Rotate-Move (CRM) forgery

- > Copies a region and rotates it before pasting
- > Example of CRM forgery









## **Related works**

### Copy-move forgery

- > Structured features of small blocks
  - DCT coefficients by Fridrich et al.
  - PCA coefficients by Farid et al.
  - DWT-SVD coefficients by Luo et al.
  - Blur invariant moments by Mahdan et al.

#### Copy-rotate-move forgery

- Fourier-Mellin Transform
  - Bayram *et al*.
- > Summation of angle values of log-polar mapped block
  - Bravo-Solorio *et al.*
- > SIFT keypoints based method
  - Huang et al., Amerini et al., and Pan et al.

# Zernike moments (1/2)

### Zernike moments

> 
$$A_{nm} = \frac{n+1}{\pi} \int \int_{x^2+y^2 \le 1} f(x,y) V_{nm}^*(\rho,\theta) dx dy$$
  
Where  $V_{nm}(\rho,\theta) = R_{nm}(\rho) \exp(jm\theta)$ ,  
 $R_{nm}(\rho) = \sum_{s=0}^{(n-|m|)/2} \frac{(-1)^s [(n-s)!] \rho^{n-2s}}{s! (\frac{n+|m|}{2}-s)! (\frac{n-|m|}{2}-s)!}$ 

### Properties

- > Insensitivity to image noise
- > Ability to provide faithful image representation
- Rotational invariance
  - Magnitude of the Zernike moment



## Zernike moments (2/2)

#### Rotational invariance

> Zernike moment in the polar coordinates

$$A_{nm} = \frac{n+1}{\pi} \int_0^{2\pi} \int_0^1 f(\rho,\theta) R_{nm}(\rho) \exp(-jm\theta)\rho \ d\rho \, d\theta$$

> Zernike moment of the rotated Image

$$A'_{nm} = \frac{n+1}{\pi} \int_0^{2\pi} \int_0^1 f(\rho, \theta - \alpha) R_{nm}(\rho) \exp(-jm\theta) \rho \, d\rho \, d\theta$$

> By change of variable  $\theta_1 = \theta - \alpha$ 

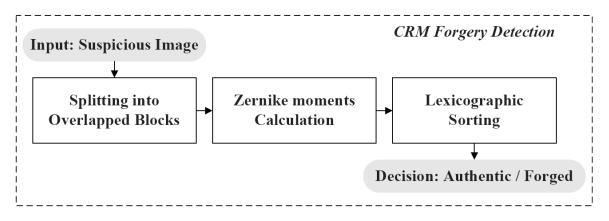
$$A'_{nm} = \frac{n+1}{\pi} \int_0^{2\pi} \int_0^1 f(\rho, \theta_1) R_{nm}(\rho) \exp(-jm(\theta_1 + \alpha))\rho \, d\rho \, d\theta_1$$

$$= \left[\frac{n+1}{\pi} \int_0^{2\pi} \int_0^1 f(\rho,\theta_1) R_{nm}(\rho) \exp(-jm\,\theta_1)\rho \,\,d\rho \,d\theta_1\right] \exp(-jm\alpha)$$

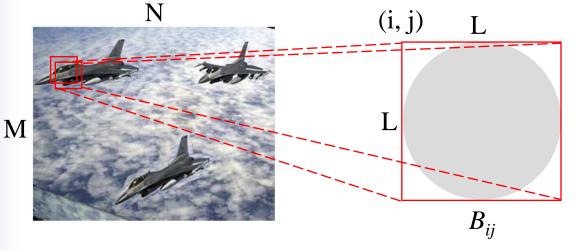
$$= A_{nm} \exp(-jm\alpha).$$

# Copy–Rotate–Move Forgery Detection (1/3)

Procedure



Feature Extraction



$$\mathbf{V}_{ij} = getZernikeMoments(B_{ij}, n)$$

$$N_{blocks} = (M - L + 1) \times (N - L + 1)$$
$$N_{moments} = \sum_{i=0}^{n} \left( \left\lfloor \frac{i}{2} \right\rfloor + 1 \right)$$
$$\mathbf{Z} = \begin{bmatrix} \mathbf{V}_{00} \\ \dots \\ \mathbf{V}_{(M-L)(N-L)} \end{bmatrix}$$

## Copy–Rotate–Move Forgery Detection (2/3)

#### Detection Criteria

> Euclidean distance between two adjacent pair of feature vector

$$\hat{\mathbf{Z}}_{p} = \left(\hat{z}_{1}^{p}, \hat{z}_{2}^{p}, ..., \hat{z}_{N_{moments}-1}^{p}, \hat{z}_{N_{moments}}^{p}\right) ,$$

$$\hat{\mathbf{Z}}_{p+1} = \left(\hat{z}_1^{p+1}, \hat{z}_2^{p+1}, ..., \hat{z}_{N_{moments}-1}^{p+1}, \hat{z}_{N_{moments}}^{p+1}\right) ,$$

$$\sqrt{\sum_{q=1}^{N_{moments}} \left( z_q^p - z_q^{p+1} \right)^2} < D_1$$

Actual distance of two image blocks

$$\sqrt{(i-k)^2 + (j-l)^2} > D_2$$
,

where 
$$\hat{\mathbf{Z}}_p = V_{ij}$$
 and  $\hat{\mathbf{Z}}_{p+1} = V_{kl}$ 

# Copy–Rotate–Move Forgery Detection (3/3)

### Complexity Analysis

- > Calculation of Zernike polynomials
  - $O(N_{moments})$
- > Computing Zernike moments from each overlapped block
  - $O(N_{blocks} \times N_{moments} \times L^2)$
- Lexicographical sorting
  - $O(N_{moments} \times N_{blocks} \times \log N_{blocks})$



## **Experimental Results (1/6)**

#### Measuring the Forgery

> Adopted Precision, Recall, and F1-measure

•  $Precision = \frac{(Forged Region \cap Detected Region)}{Detected Region} \times 100 [\%]$  $Recall = \frac{(Forged Region \cap Detected Region)}{Forged Region} \times 100 [\%]$ 

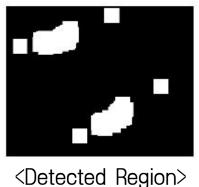
$$F_1 - measure = \frac{2}{\frac{1}{P} + \frac{1}{R}} = \frac{2PR}{P+R}$$



<Suspicious Image>



<Forged Region>



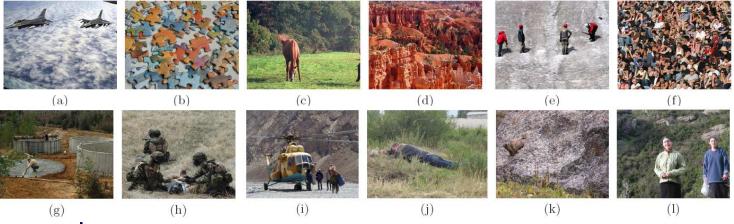


<Forged Region ∩ Detected Region>



## **Experimental Results (2/6)**

#### Images used in the experiments



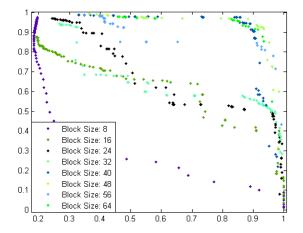
#### Parameters

- > M, N, and L: 400, 320, and 24, respectively.
- > Degree of Zernike Moments: 5
- > Threshold
  - **D1**: 300, D2: 50
- > Size of Forged Region: 100 X 70

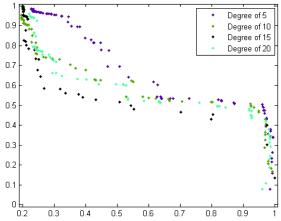


### **Experimental Results (3/6)**

Precision-Recall curve by change of block size



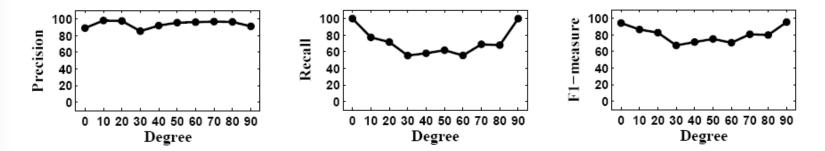
Precision-Recall curve by change of degree of zernike moments



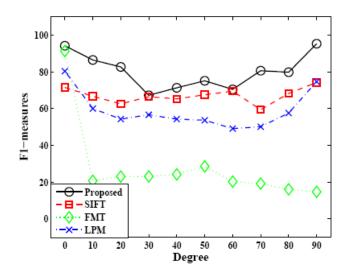


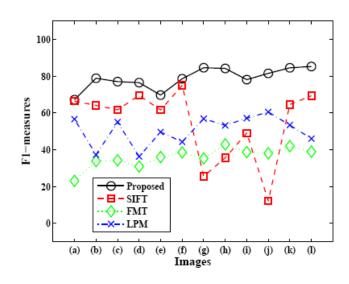
### **Experimental Results (4/6)**

CRM forgery detection results for image (a)



Detection results for CRM among several detectors

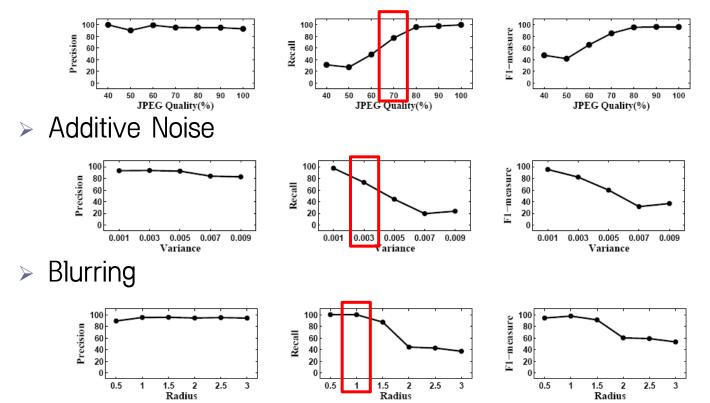




### **Experimental Results (5/6)**

#### Test for Intended Distortions for (a)

#### > JPEG compression



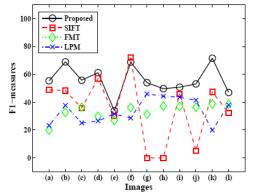


### **Experimental Results (6/6)**

### Test for Combined Manipulation

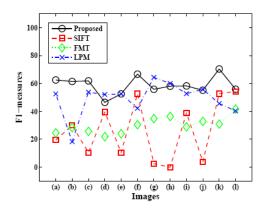
> CRM of 10°, AWGN with var = 0.003, JPEG compression (QF=80%)





> CRM of 10°, Blurring with radius = 1, JPEG compression (QF=80%)







### Conclusion

- With the rapid progress of image processing technology
  - > An appropriate forensic application has become more important
- Copy-Rotate-Move detection scheme
  - Calculate the magnitude of Zernike moments
  - > Then sorted in lexicographical order
  - > Investigate the similarity of adjacent vectors

### Future works

- Weak against scaling or the other tampering based on Affine transform
- > Adopt an efficient data structure to represent nearest neighbors